



APEX DYNAMICS, INC.

**HIGH PRECISION
HIGH SPEED
PLANETARY GEARBOX**

AD / ADR / ADS Series



Stainless



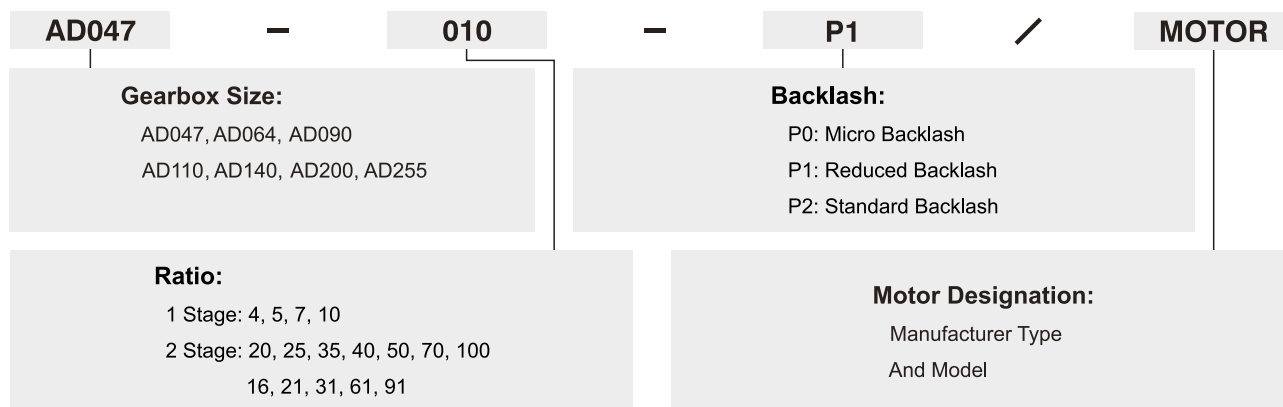
Apex Dynamics, Inc. is the world's most productive manufacturer of servomotor drive planetary gearboxes for precision automation machinery. From our 800,000+ square foot ISO 9001:2008 manufacturing facility, based in Taichung, Taiwan, we manufacture to stock using the newest precision machine tools and quality test and inspection equipment. Complete focus on quality and precision allows us to produce our high quality gearheads at precision levels down to less than 1 arc minute (1/60 th of a degree), with consistency and high reliability.

Based on more than twenty years of accumulated manufacturing and marketing experience, plus the highest level of technical production capabilities, Apex Dynamics, Inc. designs and builds technically advanced, high speed, low backlash servo application planetary gearboxes. Our Break through patented technology (over 6 patents), provides the customer with the optimum high precision helical reducer at a reasonable price. We are continuously improving processes, finding proper and effective methods to provide customers new solutions for difficult applications, and developing new products.

The primary focus in daily operation is quality. We pride ourselves on our dedication to quality; our duty - is customer satisfaction.

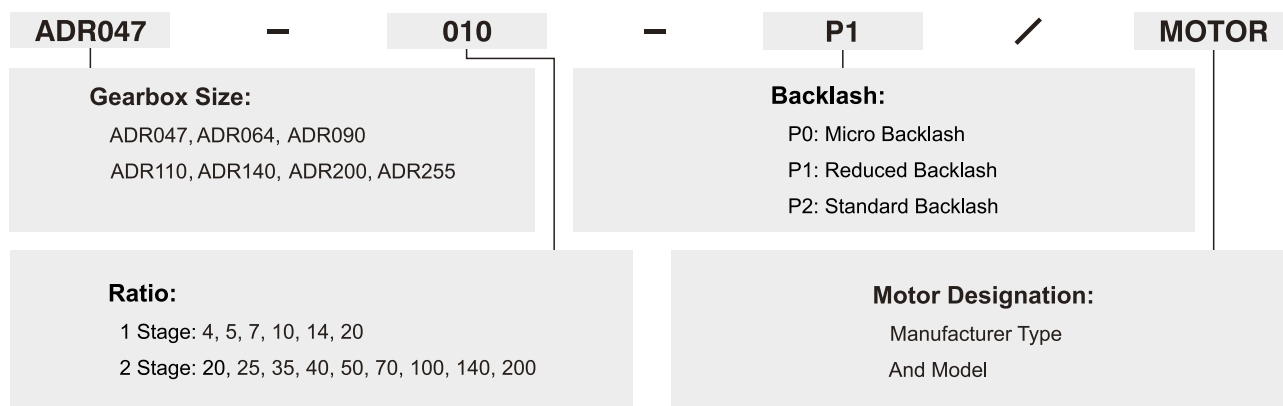


AD Series Ordering Code



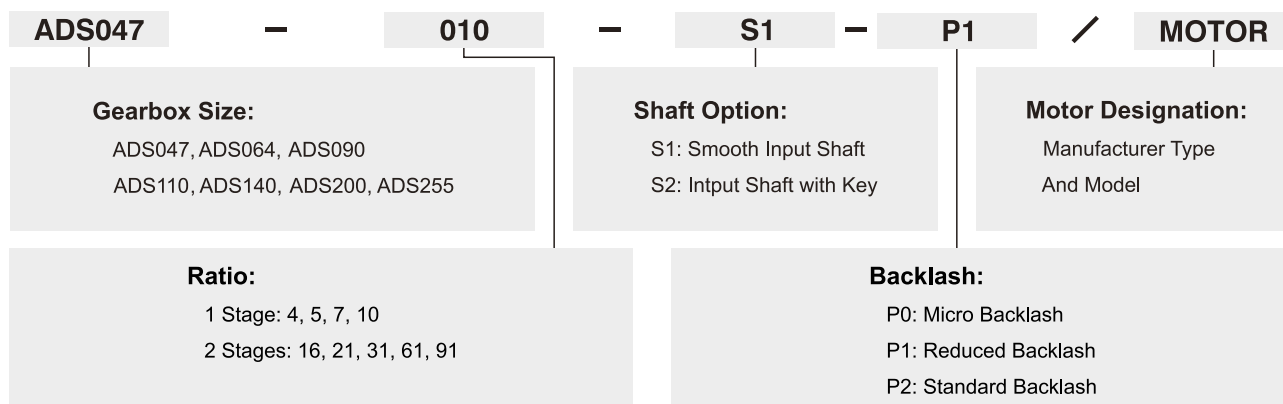
Ordering Example: AD047-010-P1 / SIEMENS 1FT6 041-4AF71

ADR Series Ordering Code



Ordering Example: ADR047-010-P1 / SIEMENS 1FT5 034-OAK71

ADS Series Ordering Code



Ordering Example: ADS047-010-S1-P1 / SIEMENS 1FT5 034-OAK71



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Specifications / AD Series

Gearbox Performance

Model No.		Stage	Ratio ⁽¹⁾	AD047	AD064	AD090	AD110	AD140	AD200	AD255
Nominal Output Torque T_{2N}	Nm	1	4	19	48	130	270	560	1,100	1,700
			5	22	60	160	330	650	1,200	2,000
			7	19	50	140	300	550	1,100	1,800
			10	14	40	100	230	450	900	1,500
		2	20	19	48	130	270	560	1,100	1,700
			25	22	60	160	330	650	1,200	2,000
			35	19	50	140	300	550	1,100	1,800
			40	19	48	130	270	560	1,100	1,700
			50	22	60	160	330	650	1,200	2,000
			70	19	50	140	300	550	1,100	1,800
			100	14	40	100	230	450	900	1,500
			16	19	48	130	270	560	1,100	1,700
			21	22	60	160	330	650	1,200	2,000
			31	19	50	140	300	550	1,100	1,800
			61	19	50	140	300	550	1,100	1,800
			91	14	40	100	230	450	900	1,500
Emergency Stop Torque $T_{2NOT}^{(2)}$	Nm	1,2	4~100	3 times of Nominal Output Torque						
Nominal Input Speed n_{iN}	rpm	1,2	4~100	5,000	5,000	4,000	4,000	3,000	3,000	2,000
Max. Input Speed n_{iB}	rpm	1,2	4~100	10,000	10,000	8,000	8,000	6,000	6,000	4,000
Micro Backlash P0	arcmin	1	4~10	-	-	≤1	≤1	≤1	≤1	≤1
		2	20~100	-	-	-	≤3	≤3	≤3	≤3
Reduced Backlash P1	arcmin	1	4~10	≤3	≤3	≤3	≤3	≤3	≤3	≤3
		2	20~100	≤5	≤5	≤5	≤5	≤5	≤5	≤5
Standard Backlash P2	arcmin	1	4~10	≤5	≤5	≤5	≤5	≤5	≤5	≤5
		2	20~100	≤7	≤7	≤7	≤7	≤7	≤7	≤7
Torsional Rigidity	Nm/arcmin	1,2	4~100	7	13	31	82	151	440	1,006
Max. Tilting Moment M_{2K}	Nm	1,2	4~100	55	75	190	300	1,300	2,930	5,500
Max. Axial Load $F_{2aB}^{(3)}$	N	1,2	4~100	990	1,050	2,850	2,990	10,590	16,660	29,430
Efficiency η	%	1	4~10	≥97%						
		2	20~100	≥94%						
Weight	kg	1	4~10	0.7	1.2	3.0	5.6	11.9	31.6	56.1
		2	20~100	1.0	1.6	3.7	7.3	15.9	36.9	70.4
Operating Temp	°C	1,2	4~100	-10°C~90°C						
Lubrication				Synthetic lubrication oils						
IP Level		1,2	4~100	IP65						
Mounting Position		1,2	4~100	all directions						
Noise ⁽⁴⁾	dB(A)	1,2	4~100	≤56	≤58	≤60	≤63	≤65	≤67	≤70

Gearbox Inertia

Model No.		Stage	Ratio ⁽¹⁾	AD047	AD064	AD090	AD110	AD140	AD200	AD255
Moments of Inertia J_i	kg · cm ²	1	4	0.03	0.14	0.51	2.87	7.54	25.03	58.31
			5	0.03	0.13	0.47	2.71	7.42	23.29	53.27
			7	0.03	0.13	0.45	2.62	7.14	22.48	50.97
			10	0.03	0.13	0.44	2.57	7.03	22.51	50.56
		2	20	0.03	0.03	0.13	0.47	2.71	7.42	23.29
			25	0.03	0.03	0.13	0.47	2.71	7.42	23.29
			35	0.03	0.03	0.13	0.47	2.71	7.42	23.29
			40	0.03	0.03	0.13	0.44	2.57	7.03	22.51
			50	0.03	0.03	0.13	0.44	2.57	7.03	22.51
			70	0.03	0.03	0.13	0.44	2.57	7.03	22.51
			100	0.03	0.03	0.13	0.44	2.57	7.03	22.51
			16	0.03	0.03	0.13	0.47	2.71	7.42	23.29
			21	0.03	0.03	0.13	0.47	2.71	7.42	23.29
			31	0.03	0.03	0.13	0.44	2.57	7.03	22.51
			61	0.03	0.03	0.13	0.44	2.57	7.03	22.51
			91	0.03	0.03	0.13	0.44	2.57	7.03	22.51

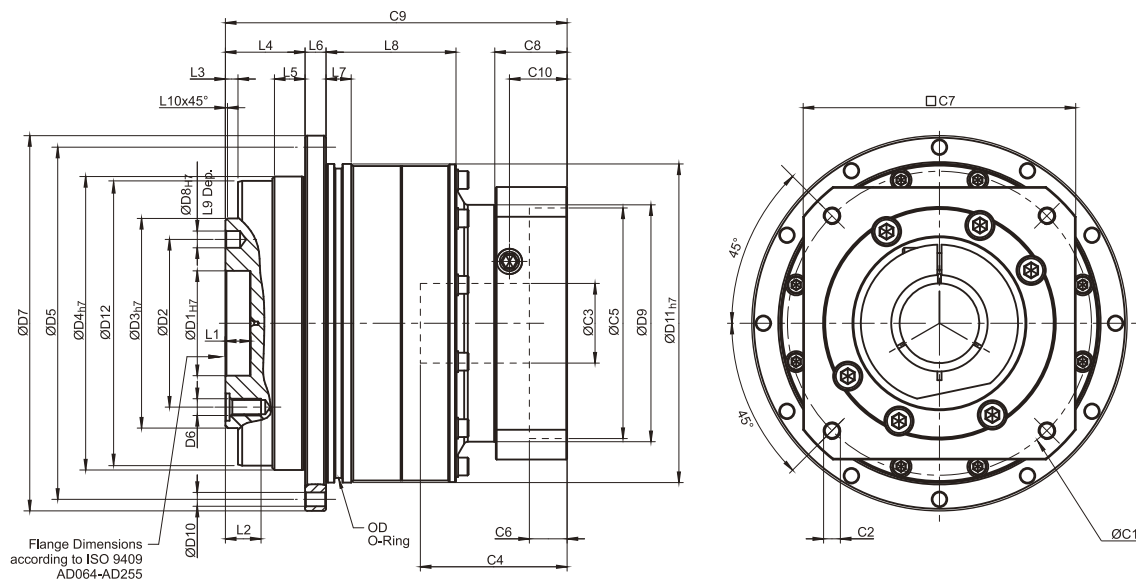
(1) Ratio ($i=N_{in}/N_{out}$)(2) Max. acceleration torque $T_{2B} = 60\%$ of T_{2NOT}

(3) Applied to the output shaft center at 100 rpm

(4) The dB values are measured by gearbox with ratio 10 (1-stage) or ratio 100 (2-stage), no loading at 3,000 RPM or at the respective Nominal Input Speed by bigger model size.

By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.

Dimensions (1-stage, Ratio $i=4\sim 10$) / AD Series

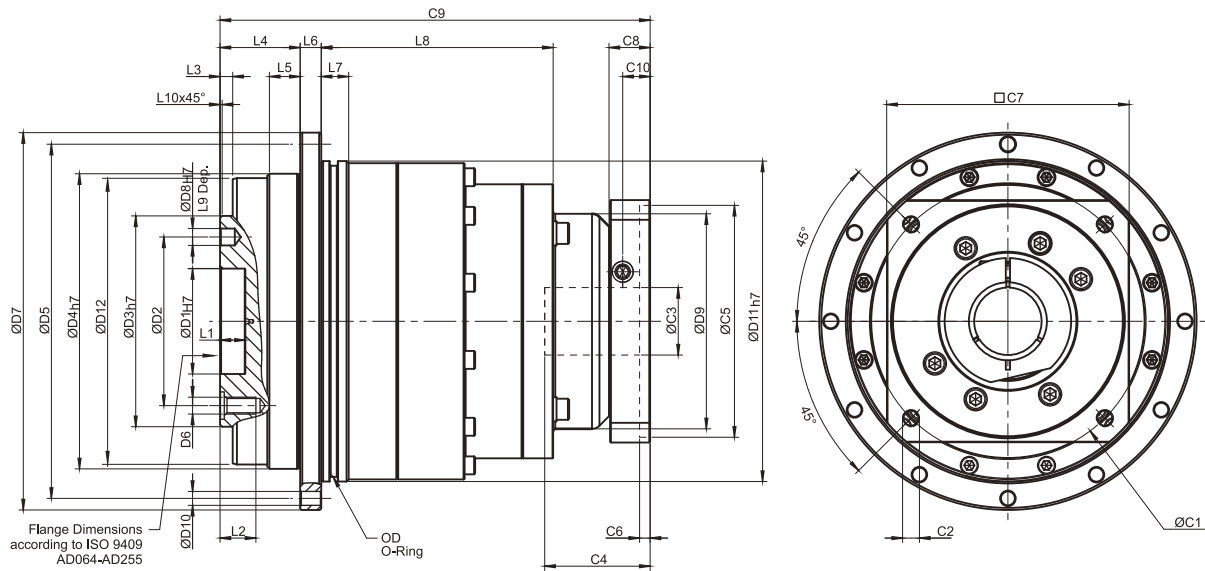


[unit: mm]

Dimension	AD047	AD064	AD090	AD110	AD140	AD200	AD255
D1 _{H7}	12	20	31.5	40	50	80	100
D2	20	31.5	50	63	80	125	140
D3 _{H7}	28	40	63	80	100	160	180
D4 _{H7}	47	64	90	110	140	200	255
D5	67	79	109	135	168	233	280
D6	4 x M3 x 0.5P	7 x M5 x 0.8P	7 x M6 x 1P	11 x M6 x 1P	11 x M8 x 1.25P	11 x M10 x 1.5P	12 x M16 x 2P
D7	72	86	118	145	179	247	300
D8 _{H7}	3	5	6	6	8	10	12
D9	45.5	55	77	90	113	138	175
D10	8 x 3.4	8 x 4.5	8 x 5.5	8 x 5.5	12 x 6.6	12 x 9	16 x 13.5
D11 _{H7}	60	70	95	120	152	212	255
D12	46.2	63.2	89.2	109.2	139.2	199.2	254.2
L1	4	8	12	12	12	16	20
L2	6.5	8	13.5	13.5	17	22.5	30.5
L3	3	3	6	6	6	8	12
L4	19.5	19.5	30	29	38	50	66
L5	7	7	10	10	14.6	15	20
L6	4	4	7	8	10	12	18
L7	5	7.7	8	10	12	15	20
L8	18.5	28.5	27	37	62	69.5	82
L9	4	6	7	7	7	10	10
L10	0.5	0.5	1	1	1	1	1
C1 ¹	46	70	100	130	165	215	235
C2 ¹	M4 x 0.7P	M5 x 0.8P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M12 x 1.75P	M12 x 1.75P
C3 ¹	≤11 / ≤12 ²	≤14 / ≤16 ²	≤19 / ≤24	≤32	≤38	≤48	≤55
C4 ¹	30	34	40	50	60	85	116
C5 ¹	30	50	80	110	130	180	200
C6 ¹	3.5	8	4	5	6	6	6
C7 ¹	48	60	90	115	142	190	220
C8 ¹	19.5	19	17	19.5	22.5	29	63
C9 ¹	70	82.5	99.5	121.5	151	199.5	256.5
C10 ¹	13.25	13.5	10.75	13	15	20.75	53.5
OD	56 x 2	66 x 2	90 x 3	110 x 3	145 x 3	200 x 5	238 x 5

1. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.
 2. AD047 ratio 5, 10 offers C3 ≤ 12 option; AD064 ratio 5, 10 offers C3 ≤ 16 option.

Dimensions (2-stage, Ratio $i=20\sim 100$) / AD Series

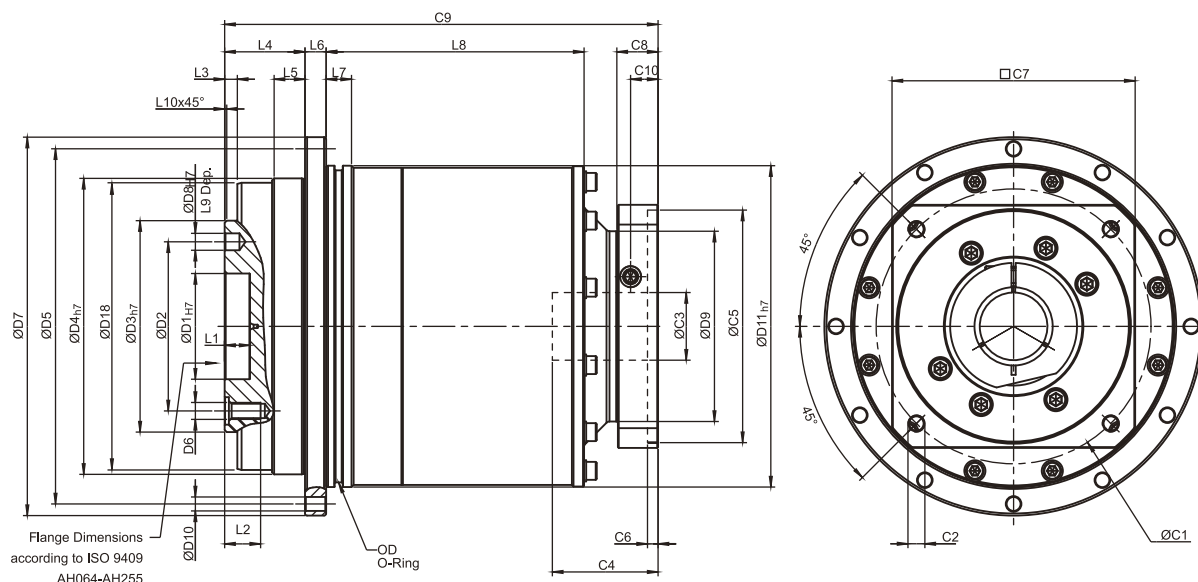


[unit: mm]

Dimension	AD047	AD064	AD090	AD110	AD140	AD200	AD255
D1 _{H7}	12	20	31.5	40	50	80	100
D2	20	31.5	50	63	80	125	140
D3 _{H7}	28	40	63	80	100	160	180
D4 _{H7}	47	64	90	110	140	200	255
D5	67	79	109	135	168	233	280
D6	4 x M3 x 0.5P	7 x M5 x 0.8P	7 x M6 x 1P	11 x M6 x 1P	11 x M8 x 1.25P	11 x M10 x 1.5P	12 x M16 x 2P
D7	72	86	118	145	179	247	300
D8 _{H7}	3	5	6	6	8	10	12
D9	45.5	45.5	53.4	77	102	125	160
D10	8 x 3.4	8 x 4.5	8 x 5.5	8 x 5.5	12 x 6.6	12 x 9	16 x 13.5
D11 _{H7}	60	70	95	120	152	212	255
D12	46.2	63.2	89.2	109.2	139.2	199.2	254.2
L1	4	8	12	12	12	16	20
L2	6.5	8	13.5	13.5	17	22.5	30.5
L3	3	3	6	6	6	8	12
L4	19.5	19.5	30	29	38	50	66
L5	7	7	10	10	14.6	15	20
L6	4	4	7	8	10	12	18
L7	5	7.7	8	10	12	15	20
L8	54.5	65	60	87.5	110	132.5	148
L9	4	6	7	7	7	10	10
L10	0.5	0.5	1	1	1	1	1
C1 ³	46	46	70	100	130	165	215
C2 ³	M4 x 0.7P	M4 x 0.7P	M5 x 0.8P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M12 x 1.75P
C3 ³	≤11 / ≤12	≤11 / ≤12	≤14 / ≤15.875 / ≤16	≤19 / ≤24	≤32	≤38	≤48
C4 ³	30	30	34	40	50	60	85
C5 ³	30	30	50	80	110	130	180
C6 ³	3.5	3.5	8	4	5	6	6
C7 ³	48	48	60	90	115	142	190
C8 ³	19.5	19.5	19	17	19.5	22.5	29
C9 ³	97.5	108	134	160	204	248	311.5
C10 ³	13.25	13.25	13.5	10.75	13	15	20.75
OD	56 x 2	66 x 2	90 x 3	110 x 3	145 x 3	200 x 5	238 x 5

3. C1-C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

Dimensions (2-stage, Ratio $i = 16 \sim 91$) / AD Series



[unit: mm]

Dimension	AD047	AD064	AD090	AD110	AD140	AD200	AD255
D1 ^{H7}	12	20	31.5	40	50	80	100
D2	20	31.5	50	63	80	125	140
D3 ^{h7}	28	40	63	80	100	160	180
D4 ^{h7}	47	64	90	110	140	200	255
D5	67	79	109	135	168	233	280
D6	4 x M3 x 0.5P	7 x M5 x 0.8P	7 x M6 x 1P	11 x M6 x 1P	11 x M8 x 1.25P	11 x M10 x 1.5P	12 x M16 x 2P
D7	72	86	118	145	179	247	300
D8 ^{H7}	3	5	6	6	8	10	12
D9	45.5	45.5	55	77	90	113	138
D10	8 x 3.4	8 x 4.5	8 x 5.5	8 x 5.5	12 x 6.6	12 x 9	16 x 13.5
D11 ^{h7}	60	70	95	120	152	212	255
D18	46.2	63.2	89.2	109.2	139.2	199.2	254.2
L1	4	8	12	12	12	16	20
L2	6.5	8	13.5	13.5	17	22.5	30.5
L3	3	3	6	6	6	8	12
L4	19.5	19.5	30	29	38	50	66
L5	7	7	10	10	14.6	15	20
L6	4	4	7	8	10	12	18
L7	5	7.7	8	10	12	15	20
L8	52.5	28.5	32	37	122	79.5	82
L9	4	6	7	7	7	10	10
L10	0.5	0.5	1	1	1	1	1
C1 ^d	46	46	70	100	130	165	215
C2 ^d	M4 x 0.7P	M4 x 0.7P	M5 x 0.8P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M12 x 1.75P
C3 ^d	≤11 / ≤12	≤11 / ≤12	≤14 / ≤15.875 / ≤16	≤19 / ≤24	≤32	≤38	≤48
C4 ^d	30	30	34	40	50	60	85
C5 ^d	30	30	50	80	110	130	180
C6 ^d	3.5	3.5	8	4	5	6	6
C7 ^d	48	48	60	90	115	142	190
C8 ^d	19.5	19.5	19	17	19.5	22.5	29
C9 ^d	100	106	130.5	149	205	247.5	323
C10 ^d	13.25	13.25	13.5	10.75	13	15	20.75
OD	56 x 2	66 x 2	90 x 3	110 x 3	145 x 3	200 x 5	238 x 5

4. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

Specifications / ADR Series

Gearbox Performance

Model No.		Stage	Ratio ⁽¹⁾	ADR047	ADR064	ADR090	ADR110	ADR140	ADR200	ADR255	
Nominal Output Torque T_{2N}	Nm	1	4	19	48	130	270	560	1,100	1,700	
			5	22	60	160	330	650	1,200	2,000	
			7	19	50	140	300	550	1,100	1,800	
			10	14	60	160	325	650	1,200	2,000	
			14	-	42	140	300	550	1,100	1,800	
			20	-	40	100	230	450	900	1,500	
		2	20	19	-	-	-	-	-	-	-
			25	22	60	160	330	650	1,200	2,000	
			35	19	50	140	300	550	1,100	1,800	
			40	19	48	130	270	560	1,100	1,700	
			50	22	60	160	330	650	1,200	2,000	
			70	19	50	140	300	550	1,100	1,800	
			100	14	40	100	230	450	900	1,500	
			140	-	-	140	300	550	1,100	1,800	
200	-	-	100	230	450	900	1,500				
Emergency Stop Torque T_{2NOTB} ⁽²⁾	Nm	1,2	4~200	3 times of Nominal Output Torque							
Nominal Input Speed n_{1N}	rpm	1,2	4~200	5,000	5,000	4,000	4,000	3,000	3,000	2,000	
Max. Input Speed n_{1B}	rpm	1,2	4~200	10,000	10,000	8,000	8,000	6,000	6,000	4,000	
Micro Backlash P0	arcmin	1	4~20	-	-	≤2	≤2	≤2	≤2	≤2	
		2	25~200	-	-	≤4	≤4	≤4	≤4	≤4	
Reduced Backlash P1	arcmin	1	4~20	≤4	≤4	≤4	≤4	≤4	≤4	≤4	
		2	25~200	≤7	≤7	≤7	≤7	≤7	≤7	≤7	
Standard Backlash P2	arcmin	1	4~20	≤6	≤6	≤6	≤6	≤6	≤6	≤6	
		2	25~200	≤9	≤9	≤9	≤9	≤9	≤9	≤9	
Torsional Rigidity	Nm/arcmin	1,2	4~200	7	13	31	82	151	440	1,006	
Max. Tilting Moment M_{2K}	Nm	1,2	4~200	55	75	190	300	1,300	2,930	5,500	
Max. Axial Load F_{2aB} ⁽³⁾	N	1,2	4~200	990	1,050	2,850	2,990	10,590	16,660	29,430	
Efficiency η	%	1	4~20	≥95%							
		2	25~200	≥92%							
Weight	kg	1	4~20	1.1	2.1	5.9	10.5	21.9	50.9	85.4	
		2	25~200	1.4	1.9	4.5	9.8	20.1	45.4	85.9	
Operating Temp	°C	1,2	4~200	-10°C~90°C							
Lubrication				Synthetic lubrication oils							
IP Level		1,2	4~200	IP65							
Mounting Position		1,2	4~200	all directions							
Noise ⁽⁴⁾	dB(A)	1,2	4~200	≤61	≤63	≤65	≤68	≤70	≤72	≤74	

Gearbox Inertia

Model No.		Stage	Ratio ⁽¹⁾	ADR047	ADR064	ADR090	ADR110	ADR140	ADR200	ADR255	
Moments of Inertia J_i	kg · cm ²	1	4~10	0.09	0.35	2.25	6.84	23.4	68.9	135.4	
			14	-	0.31	1.87	6.25	21.8	65.6	119.8	
			20	-	0.31	1.87	6.25	21.8	65.6	119.8	
		2	20	0.09	-	-	-	-	-	-	-
			25~100	0.09	0.09	0.35	2.25	6.84	23.4	68.9	
			140~200	-	-	0.31	1.87	6.25	21.8	65.6	

(1) Ratio ($i=N_{in}/N_{out}$)

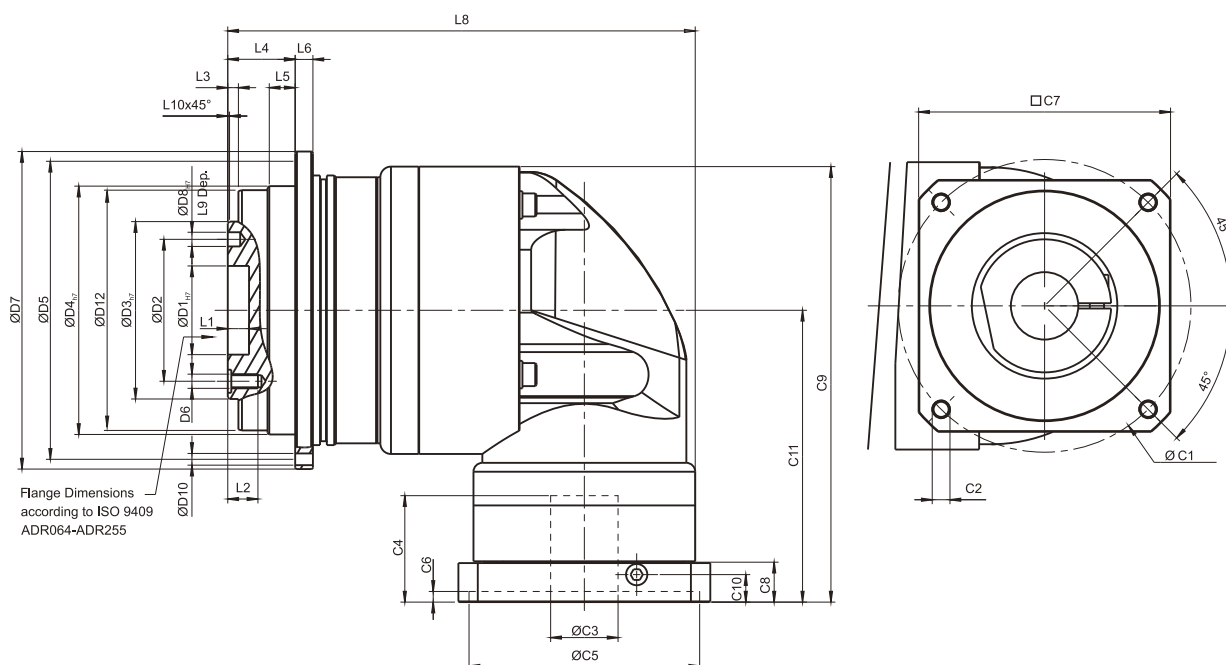
(2) Max. acceleration torque $T_{2B} = 60\%$ of T_{2NOT}

(3) Applied to the output shaft center at 100 rpm

(4) The dB values are measured by gearbox with ratio 10 (1-stage) or ratio 100 (2-stage), no loading at 3,000 RPM or at the respective Nominal Input Speed by bigger model size.

By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.

Dimensions (1-stage, Ratio $i=4\sim 20$) / ADR Series

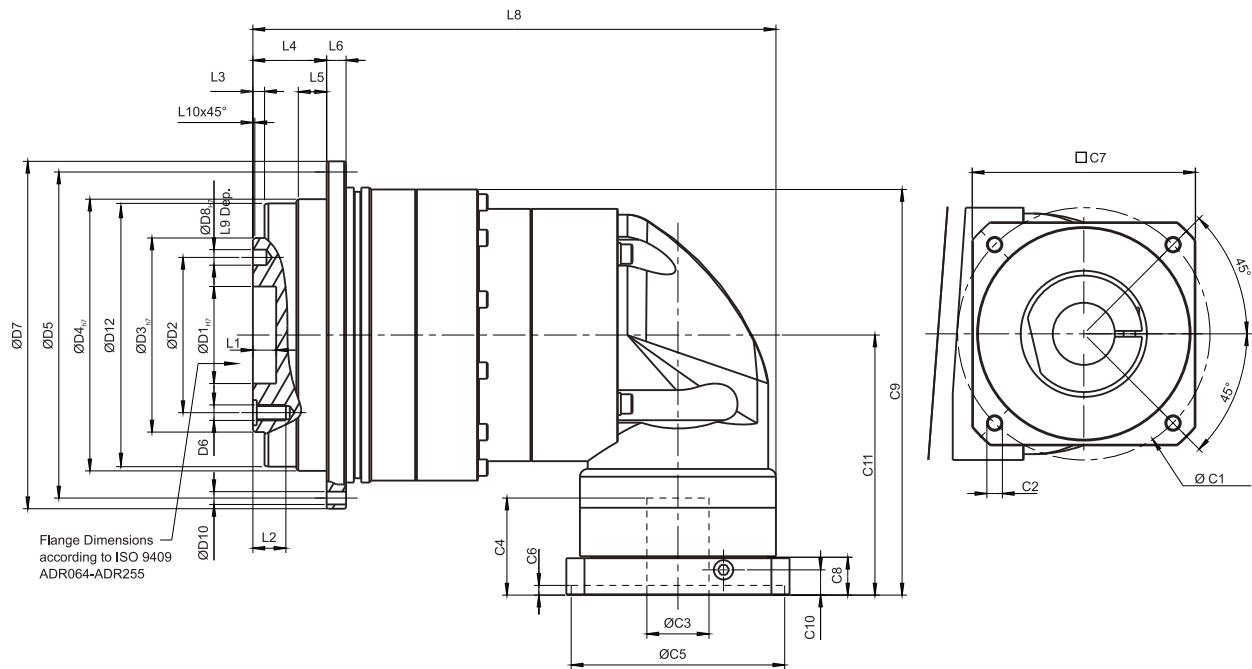


[unit: mm]

Dimension	ADR047	ADR064	ADR090	ADR110	ADR140	ADR200	ADR255
D1 _{H7}	12	20	31.5	40	50	80	100
D2	20	31.5	50	63	80	125	140
D3 _{h7}	28	40	63	80	100	160	180
D4 _{h7}	47	64	90	110	140	200	255
D5	67	79	109	135	168	233	280
D6	4 x M3 x 0.5P	7 x M5 x 0.8P	7 x M6 x 1P	11 x M6 x 1P	11 x M8 x 1.25P	11 x M10 x 1.5P	12 x M16 x 2P
D7	72	86	118	145	179	247	300
D8 _{H7}	3	5	6	6	8	10	12
D10	8 x 3.4	8 x 4.5	8 x 5.5	8 x 5.5	12 x 6.6	12 x 9	16 x 13.5
D12	46.2	63.2	89.2	109.2	139.2	199.2	254.2
L1	4	8	12	12	12	16	20
L2	6.5	8	13.5	13.5	17	22.5	30.5
L3	3	3	6	6	6	8	12
L4	19.5	19.5	30	29	38	50	66
L5	7	7	10	10	14.6	15	20
L6	4	4	7	8	10	12	18
L8	107.5	126	172.5	201	263.5	334.5	392
L9	4	6	7	7	7	10	10
L10	0.5	0.5	1	1	1	1	1
C1 ¹	46	70	100	130	165	215	235
C2 ¹	M4 x 0.7P	M5 x 0.8P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M12 x 1.75P	M12 x 1.75P
C3 ¹	≤11 / ≤12	≤14 / ≤16	≤19 / ≤24	≤32	≤38	≤48	≤55
C4 ¹	30	34	40	50	60	85	116
C5 ¹	30	50	80	110	130	180	200
C6 ¹	3.5	8	4	5	6	6	6
C7 ¹	48	60	90	115	142	190	220
C8 ¹	19.5	19	17	19.5	22.5	29	63
C9 ¹	104.25	116.5	159.5	199	245.5	316	398.5
C10 ¹	13.25	13.5	10.75	13	15	20.75	53.5
C11 ¹	74	81.5	107.5	134	164.5	213.5	268.5

1. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

Dimensions (2-stage, Ratio $i=25\sim 200$) / ADR Series



[unit: mm]

Dimension	ADR047	ADR064	ADR090	ADR110	ADR140	ADR200	ADR255
D1 _{H7}	12	20	31.5	40	50	80	100
D2	20	31.5	50	63	80	125	140
D3 _{h7}	28	40	63	80	100	160	180
D4 _{h7}	47	64	90	110	140	200	255
D5	67	79	109	135	168	233	280
D6	4 x M3 x 0.5P	7 x M5 x 0.8P	7 x M6 x 1P	11 x M6 x 1P	11 x M8 x 1.25P	11 x M10 x 1.5P	12 x M16 x 2P
D7	72	86	118	145	179	247	300
D8 _{H7}	3	5	6	6	8	10	12
D10	8 x 3.4	8 x 4.5	8 x 5.5	8 x 5.5	12 x 6.6	12 x 9	16 x 13.5
D12	46.2	63.2	89.2	109.2	139.2	199.2	254.2
L1	4	8	12	12	12	16	20
L2	6.5	8	13.5	13.5	17	22.5	30.5
L3	3	3	6	6	6	8	12
L4	19.5	19.5	30	29	38	50	66
L5	7	7	10	10	14.6	15	20
L6	4	4	7	8	10	12	18
L8	122	132.5	163	217.5	269.5	333.5	403
L9	4	6	7	7	7	10	10
L10	0.5	0.5	1	1	1	1	1
C1 ²	46	46	70	100	130	165	215
C2 ²	M4 x 0.7P	M4 x 0.7P	M5 x 0.8P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M12 x 1.75P
C3 ²	≤11 / ≤12	≤11 / ≤12	≤14 / ≤15.875 / ≤16	≤19 / ≤24	≤32	≤38	≤48
C4 ²	30	30	34	40	50	60	85
C5 ²	30	30	50	80	110	130	180
C6 ²	3.5	3.5	8	4	5	6	6
C7 ²	48	48	60	90	115	142	190
C8 ²	19.5	19.5	19	17	19.5	22.5	29
C9 ²	103.25	108.25	128.25	166.5	209	269.5	340
C10 ²	13.25	13.25	13.5	10.75	13	15	20.75
C11 ²	74	74	81.5	107.5	134	164.5	213.5

2. C1-C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

Specifications / ADS Series

Gearbox Performance

Model No.	Stage	Ratio ⁽¹⁾	ADS047	ADS064	ADS090	ADS110	ADS140	ADS200	ADS255	
Nominal Output Torque T_{2N}	1	4	19	48	130	270	560	1,100	1,700	
		5	22	60	160	330	650	1,200	2,000	
		7	19	50	140	300	550	1,100	1,800	
		10	14	40	100	230	450	900	1,500	
	2	16	19	48	130	270	560	1,100	1,700	
		21	22	60	160	330	650	1,200	2,000	
		31	19	50	140	300	550	1,100	1,800	
		61	19	50	140	300	550	1,100	1,800	
		91	14	40	100	230	450	900	1,500	
		Emergency Stop Torque $T_{2NOT}^{(2)}$	Nm	1,2	4~91	3 times of Nominal Output Torque				
Nominal Input Speed n_{1N}	rpm	1,2	4~91	5,000	5,000	4,000	4,000	3,000	3,000	2,000
Max. Input Speed n_{1B}	rpm	1,2	4~91	10,000	10,000	8,000	7,500	4,500	4,500	3,800
Micro Backlash P0	arcmin	1	4~10	-	-	≤1	≤1	≤1	≤1	≤1
		2	16~91	-	-	-	≤3	≤3	≤3	≤3
Reduced Backlash P1	arcmin	1	4~10	≤3	≤3	≤3	≤3	≤3	≤3	≤3
		2	16~91	≤5	≤5	≤5	≤5	≤5	≤5	≤5
Standard Backlash P2	arcmin	1	4~10	≤5	≤5	≤5	≤5	≤5	≤5	≤5
		2	16~91	≤7	≤7	≤7	≤7	≤7	≤7	≤7
Torsional Rigidity	Nm/arcmin	1,2	4~91	3	7	14	25	50	145	225
Max. Tilting Moment M_{2K}	Nm	1,2	4~91	55	75	190	300	1,300	2,930	5,500
Max. Axial Load	N	1,2	4~91	990	1,050	2,850	2,990	10,590	16,660	29,430
Input Max. Radial Load $F_{1RB}^{(3)}$	N	1	4~10	165	395	1,300	1,525	2,800	4,500	12,500
		2	16~91	165	165	395	1,300	1,525	2,800	4,500
Input Max. Axial Load $F_{1aB}^{(3)}$	N	1	4~10	580	1,000	1,100	980	2,700	4,700	8,000
		2	16~91	580	580	1,000	1,100	980	2,700	4,700
Efficiency η	%	1	4~10	≥97%						
		2	16~91	≥94%						
Weight	kg	1	4~10	0.8	1.4	3.4	6.7	13.5	35.0	63.8
		2	16~91	1.1	1.6	4.0	7.3	16.6	36.4	74.7
Operating Temp	°C	1,2	4~91	-10°C~90°C						
Lubrication				Synthetic lubrication oils						
IP Level		1,2	4~91	IP65						
Mounting Position		1,2	4~91	all directions						
Noise ⁽⁴⁾	dB(A)	1,2	4~91	≤56	≤58	≤60	≤63	≤65	≤67	≤70

Gearbox Inertia

Model No.	Stage	Ratio ⁽¹⁾	ADS047	ADS064	ADS090	ADS110	ADS140	ADS200	ADS255
Moments of Inertia J_1	1	4	0.06	0.21	0.87	3.65	10.27	43.05	102.68
		5	0.06	0.21	0.83	3.53	10.17	41.76	99.12
		7	0.06	0.21	0.82	3.47	9.99	41.15	97.41
		10	0.06	0.21	0.81	3.45	9.93	40.97	97.03
	2	16	0.06	0.06	0.21	0.83	3.53	10.17	41.76
		21	0.06	0.06	0.21	0.83	3.53	10.17	41.76
		31	0.06	0.06	0.21	0.83	3.53	10.17	41.76
		61	0.06	0.06	0.21	0.81	3.45	9.93	40.97
		91	0.06	0.06	0.21	0.81	3.45	9.93	40.97

(1) Ratio ($i=N_{in}/N_{out}$)

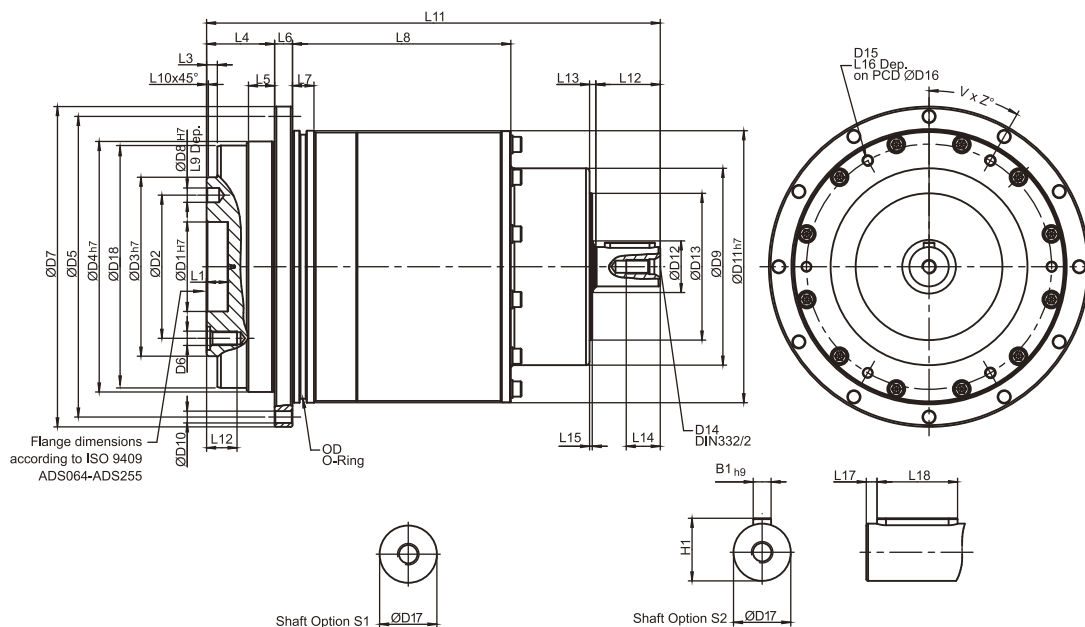
(2) Max. acceleration torque $T_{2B} = 60\%$ of T_{2NOT}

(3) Applied to the output shaft center at 100 rpm

(4) The dB values are measured by gearbox with ratio 10 (1-stage) or ratio 100 (2-stage), no loading at 3,000 RPM or at the respective Nominal Input Speed by bigger model size.

By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.

Dimensions (2-stage, Ratio $i = 16 \sim 91$) / ADS Series

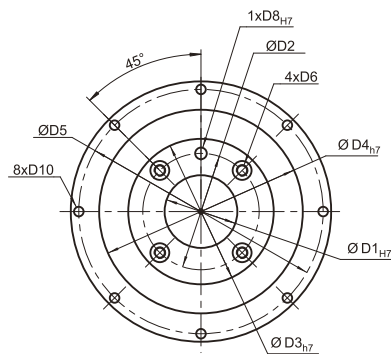


[unit: mm]

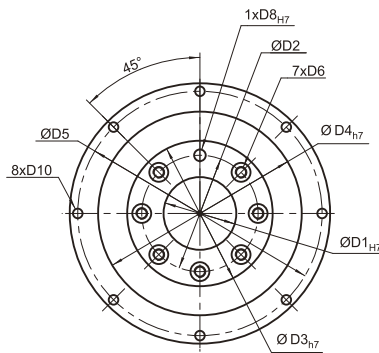
Dimension	ADS047	ADS064	ADS090	ADS110	ADS140	ADS200	ADS255
D1 _{H7}	12	20	31.5	40	50	80	100
D2	20	31.5	50	63	80	125	140
D3 _{H7}	28	40	63	80	100	160	180
D4 _{H7}	47	64	90	110	140	200	255
D5	67	79	109	135	168	233	280
D6	4 x M3 x 0.5P	7 x M5 x 0.8P	7 x M6 x 1P	11 x M6 x 1P	11 x M8 x 1.25P	11 x M10 x 1.5P	12 x M16 x 2P
D7	72	86	118	145	179	247	300
D8 _{H7}	3	5	6	6	8	10	12
D9	43	48	68	86	110	132	182
D10	8 x 3.4	8 x 4.5	8 x 5.5	8 x 5.5	12 x 6.6	12 x 9	16 x 13.5
D11 _{H7}	60	70	95	120	152	212	255
D12	22	22	22	22	30	40	75
D13	37	37	50	62	82	108	145
D14	M4 x 0.7P	M4 x 0.7P	M4 x 0.7P	M5 x 0.8P	M8 x 1.25P	M12 x 1.75P	M16 x 2P
D15	M3 x 0.5P	M3 x 0.5P	M4 x 0.7P	M5 x 0.8P	M6 x 1P	M8 x 1.25P	M10 x 1.5P
D16	51.5	61.5	84	107	137	193	235
D17 _{K6}	11	11	14	16	22	32	40
D18	46.2	63.2	89.2	109.2	139.2	199.2	254.2
L1	4	8	12	12	12	16	20
L2	6.5	8	13.5	13.5	17	22.5	30.5
L3	3	3	6	6	6	8	12
L4	19.5	19.5	30	29	38	50	66
L5	7	7	10	10	14.6	15	20
L6	4	4	7	8	10	12	18
L7	5	7.7	8	10	12	15	20
L8	62.5	63.5	67	82	122	79.5	177
L9	4	6	7	7	7	10	10
L10	0.5	0.5	1	1	1	1	1
L11	119.5	125.5	158.5	188	253.5	314.5	419.5
L12	18	18	22	28	36	58	82
L13	2.5	2.5	2.5	3.5	3.5	3.5	4.5
L14	10	10	10	12.5	19	28	36
L15	1.5	1.5	1.5	1.5	1.5	1.5	1.5
L16	5.5	5.5	7	9	11	14	18
L17	2	2	2	3	3	6	6
L18	14	14	18	22	28	45	70
B1 _{H9}	4	4	5	5	6	10	12
H1	12.5	12.5	16	18	24.5	35	43
OD	56 x 2	66 x 2	90 x 3	110 x 3	145 x 3	200 x 5	238 x 5
V	4	4	4	4	6	6	6
Z	45	45	45	45	30	30	30

Output Dimensions

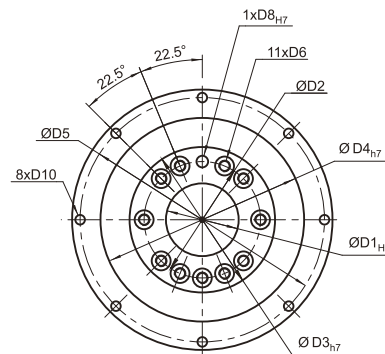
**AD 047
ADR 047
ADS 047**



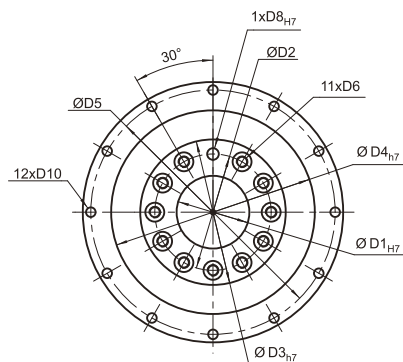
**AD 064 / AD 090
ADR 064 / ADR 090
ADS 064 / ADS 090**



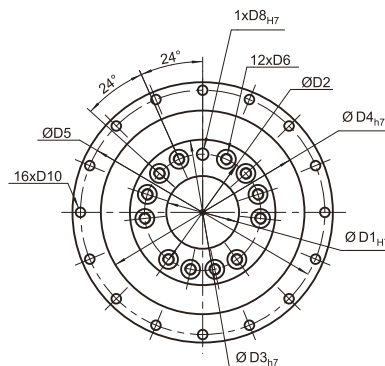
**AD 110
ADR 110
ADS 110**



**AD 140 / AD 200
ADR 140 / ADR 200
ADS 140 / ADS 200**



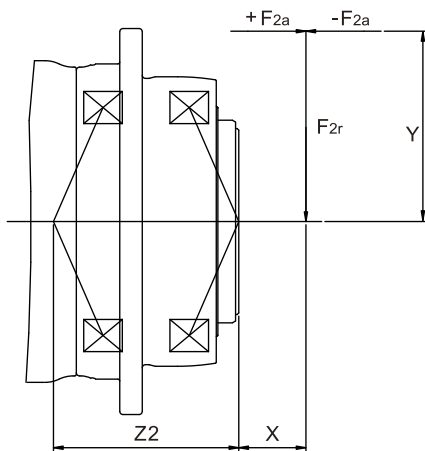
**AD 255
ADR 255
ADS 255**



[unit: mm]

Dimension	AD047	AD064	AD090	AD110	AD140	AD200	AD255
	ADR047	ADR064	ADR090	ADR110	ADR140	ADR200	ADR255
	ADS047	ADS064	ADS090	ADS110	ADS140	ADS200	ADS255
D1 _{H7}	12	20	31.5	40	50	80	100
D2	20	31.5	50	63	80	125	140
D3 _{h7}	28	40	63	80	100	160	180
D4 _{h7}	47	64	90	110	140	200	255
D5	67	79	109	135	168	233	280
D6	M3 x 0.5P	M5 x 0.8P	M6 x 1P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M16 x 2P
D8 _{H7}	3	5	6	6	8	10	12
D10	3.4	4.5	5.5	5.5	6.6	9	13.5

Max. Tilting Moment M_{2K}



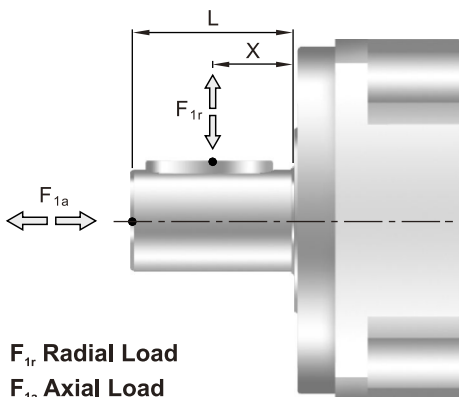
$$M_{2K} = \frac{F_{2a} * Y + F_{2r} * (X+Z2)}{1000}$$

M_{2K} : [Nm]
 F_{2a}, F_{2r} : [N]
 $X, Y, Z2$: [mm]

AD / ADR / ADS	047	064	090	110	140	200	255
Z2 [mm]	37.9	46.2	63.1	75.5	92.2	119.2	148.8

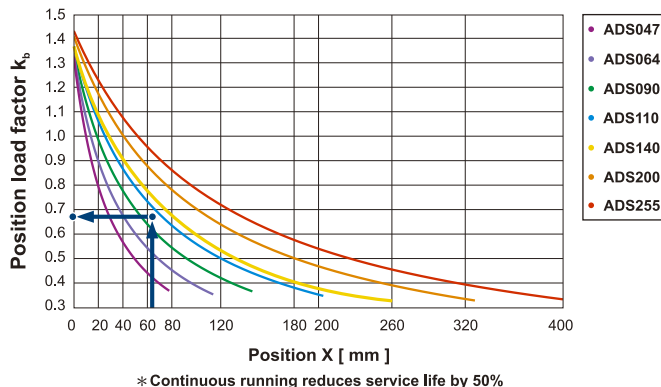
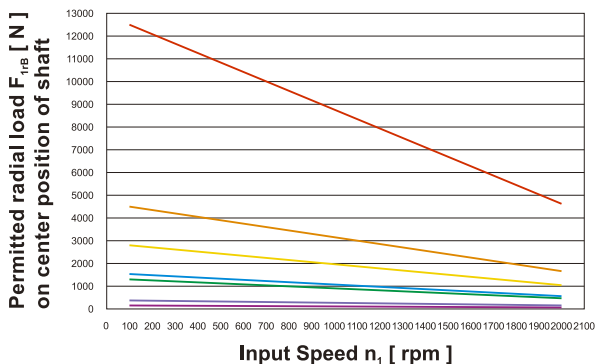
Note : Applied to the output flange center at 100 rpm.

ADS-Permitted Radial and Axial Loads



The permitted radial and axial loads on input shaft of the gearbox depend on the design of the gearbox supporting bearings. APEX use the extension straddle oversized ball bearing design. It can take heavy load from both axes.

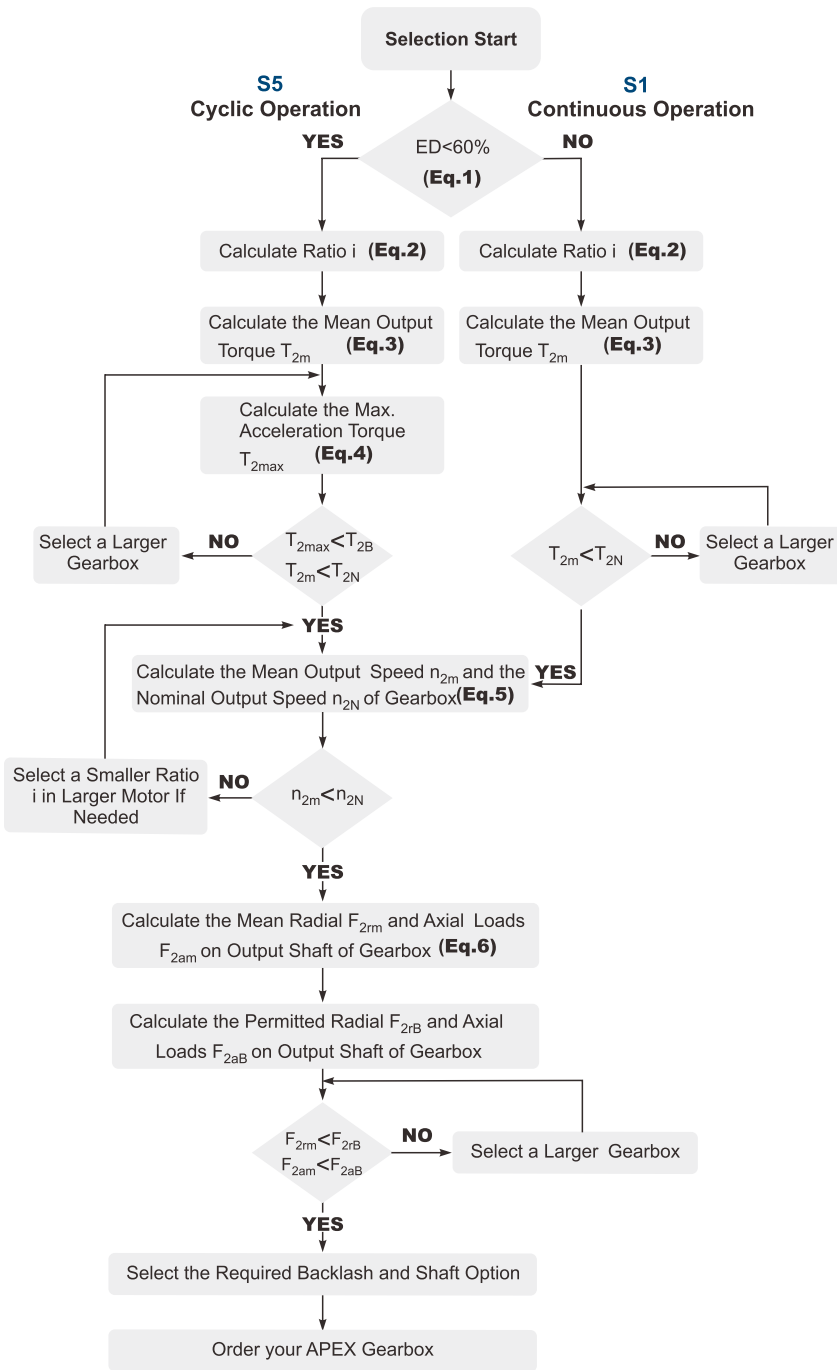
F_{1r} Radial Load
 F_{1a} Axial Load



If radial force F_{1r} is exert on the center of the output shaft $X=1/2 \times L$. The permitted radial load is given on above diagram.

If radial force F_{1r} is not exert on the center of the output shaft $X < 1/2 \times L$ or $X > 1/2 \times L$. The permitted radial and axial loads can be calculated by the position load factor K_b on the above diagram.

Selection of the optimum gearbox



Recommended (for S5 Cycle Operation)

The general design is given for

$$\frac{J_L}{i^2} \leq 4 \times J_m$$

The optimal design is given for

$$\frac{J_L}{i^2} \cong J_m$$

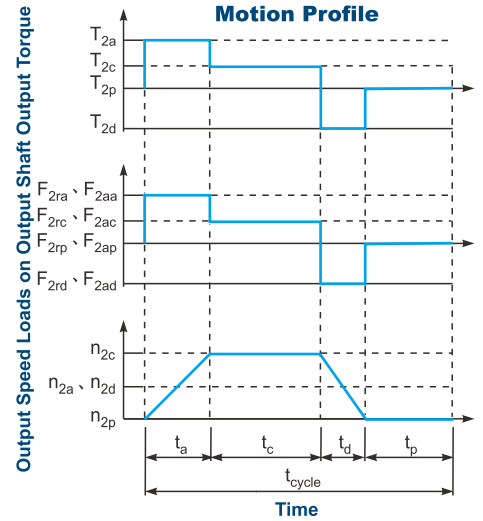
J_L Load Inertia

J_m Motor Inertia

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$$1. ED = \frac{t_a + t_c + t_d}{t_{cycle}} \times 100\% .$$

Index : a. Acceleration, c. Constant,
d. Deceleration, p. Pause (Eq. 1)

$$2. i \cong \frac{n_m}{n_{work}}$$

n_m Output Speed of the Motor
 n_{work} Working Speed (Eq. 2)

$$3. T_{2m} = \sqrt[3]{\frac{n_{2a} \times t_a \times T_{2a}^3 + n_{2c} \times t_c \times T_{2c}^3 + n_{2d} \times t_d \times T_{2d}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

(Eq. 3)

$$4. T_{2max} = T_{mB} \times i \times K_s \times \eta$$

where K_s is

K_s	No. of Cycles / hr
1.0	0 ~ 1,000
1.1	1,000 ~ 1,500
1.3	1,500 ~ 2,000
1.6	2,000 ~ 3,000
1.8	3,000 ~ 5,000

T_{mB} Max. Output Torque of the Motor

η Efficiency of the Gearbox (Eq. 4)

$$5. n_{2a} = n_{2d} = \frac{1}{2} \times n_{2c}$$

$$n_{2m} = \frac{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}{t_a + t_c + t_d}$$

$$n_{2N} = \frac{n_{1N}}{i}$$

(Eq. 5)

$$6. F_{2m} = \sqrt[3]{\frac{n_{2a} \times t_a \times F_{2ra}^3 + n_{2c} \times t_c \times F_{2rc}^3 + n_{2d} \times t_d \times F_{2rd}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

$$F_{2am} = \sqrt[3]{\frac{n_{2a} \times t_a \times F_{2aa}^3 + n_{2c} \times t_c \times F_{2ac}^3 + n_{2d} \times t_d \times F_{2ad}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

(Eq. 6)

Note



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